

SIGNIFICANCE OF FINSLER SPACES AND LAGRANGE SPACE

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ABSTRACT

Finsler geometry is a kind of differential geometry, which was begun by P. Finsler in 1918. It is regularly tried to be as a speculation of the Riemannian geometry. The particular explanation of progress of Finsler geometry can be confined into four periods.

The gigantic season of the legitimate premise of progress of Finsler geometry began in 1924, when the three geometers J. H. Taylor, J. L. Synge and L. Berwald meanwhile started the work in this field. Berwald is the squeezing man who has introduced the opportunity of relationship in the hypothesis of Finsler spaces. He is the producer of Finsler geometry and, as required, the facilitator. He has cultivated a speculation with unequivocal reference to the hypothesis of cadenced improvement in which the Ricci lemma doesn't hold perfect. J. H. Taylor gave the name 'Finsler space' to the complex outfitted with this summarized assessment.

The subsequent time period began in 1934, when E. Cartan dissipated his theory on Finsler geometry. He showed that it was to be certain possible to depict connection coefficients and as such covariant accomplices with a persuading objective that the Ricci lemma is satisfied.

KEYWORDS:

Finsler, Lagrange, Space

INTRODUCTION

All following appraisals considering the geometry of Finsler spaces were overpowered by this game plan. A couple of mathematicians have focused in on Finsler geometry along Cartan's system. They have given the perspective that the speculation has accomplished its last procedure. This speculation make express contraptions, which on a fantastically chief level sets the chance of a space, whose parts are not the spots of the key complex, yet rather the line part of last choice, which outlines a $(2n - 1)$ layered plan. This works with what Cartan called 'Euclidean association' which through unambiguous proposes may be gotten astoundingly from the key examination work.

The fourth season of history of progress of Finsler geometry began in 1963, when H. Akabar Zadeh empowered the overall hypothesis of Finsler spaces considering the geometry of relationship of fiber parties. The clarification of modernization is to spread out a general importance of relationship in Finsler spaces and to reexamine the Cartan's course of action of adages. Mathematicians and Physicists began to focus in on astounding Finsler spaces from the party illustrated by Matsumoto on the models of Finsler spaces in 1970.

In 1986, M. Matsumoto appropriated his book, Underpinnings of Finsler geometry and surprising Finsler spaces which pulled in the evaluations towards the hair-raising Finsler spaces, for instance, Berwald space, Minkowskian space, C-reducible Finsler space, semi C-reducible Finsler space, Finsler space with (α, β) - metric, Randers space, Kropina space, Matsumoto space, etc. At present works are going on the astonishing Finsler spaces.

See that we are given an end $L(x, y)$ of the line part (x_i, y_i) of a curve depicted in R . We will see L as a piece of class some spot near C^5 in the completely out of its $2n$ -inspects. Continuing on through we portray the second distance ds between two centers $P(x_i)$ and $Q(x_i + dx_i)$ of R by the affiliation

$$ds = L(x_i, dx_i),$$

then the manifold M_n equipped with the fundamental function L defining the metric is called a Finsler space, if $L(x_i, dx_i)$ satisfies the following conditions:

Condition A. The function $L(x_i, y_i)$ is positively homogeneous of degree one in y_i i.e.

$$L(x_i, ky_i) = kL(x_i, y_i), k > 0.$$

The Ricci Lemma doesn't, there of cerebrum, in Finsler space concerning Berwald's union i.e $g_{ij}(k) = 0$ for B_{γ} . Moreover, the Berwald's collusion coefficients $G_i jk$, isn't, there of mind, of the directional part y_i of the space.

These are two of the a few key parts, which have been in danger to further develop geometry which is by and large around not indistinguishable from the Riemannian geometry. We truly need to find such Finsler spaces which are not Riemannian and in which $g_{ijkl} = 0$ concerning B_{γ} other than such Finsler spaces (other than Riemannian) in which $G_i jk$ is freed from y_i

Lagrange space

In the party on Finsler geometry held at Kagoshima (Japan) in the mid year of 1985, Teacher R. Miron featured the significance of a summed up assessment, which isn't definitively endeavored to be unequivocally homogeneous. Truly, a ton of result in Finsler geometry stays fundamental without the hypothesis of homogeneity.

Since the intriguing saying "Finsler geometry" has all of the stores of giving off an impression of resembling the geometry is old, it doesn't yet draw in a general idea ignoring our general frameworks. Then again non-homogeneous mathematical thing like Lagrangians are fundamental as indicated by the point of view of uses. As needs be, the "Finsler geometry" ought to be unstuck by "Lagrange geometry".

Let M be a n -layered differentiable complex and $T(M)$ its deviation pack. A course structure $x = (x_i)$ in M prompts a stayed aware of heading framework $(x, y) = (x_i, y_i)$ in $T(M)$.

We put $\partial_i = \partial/\partial x_i$, $\partial^i = \partial/\partial y_i$ and $T_0(M) = \{(x, y) \in T(M) : y = 0\}$.

REMARKS ON CERTAIN SPECIAL FINSLER SPACES AND LAGRANGE SPACE

A Finsler tensor field $g_{ij}(x, y)$ of type $(0, 2)$ in M is known as a summed up Lagrange metric, it is symmetric and non-degenerate: $g_{ij} = g_{ji}$, $\det(g_{ij}) \neq 0$ to recall it. Particularly, a summed up Lagrange metric $g_{ij}(x, y)$ is known as a Lagrange metric when g_{ij} is given by $g_{ij} = \partial_i \partial_j L$ for some Finsler work $L(x, y)$ in M .

A summed up Lagrange metric $g_{ij}(x, y)$ is known as a summed up Finsler metric progressing forward through it is enduringly homogeneous of degree zero: $g_{ij}(x, ky) = g_{ij}(x, y)$ for $k > 0$. Particularly, a Lagrange metric $g_{ij}(x, y)$ is known as a Finsler metric for some Finsler work $L(x, y)$ in M which is unequivocally homogeneous of degree one: $L(x, ky) = kL(x, y)$ for $k > 0$.

Let (M_n, L) be a n -layered Finsler space on a differentiable complex M_n , equipped with the central work L .

In 1984 C. Shibata presented the limit in Finsler metric:

$$L^*(x, y) = f(L, \beta),$$

where $\beta = b_i(x)y^i$, $b_i(x)$ are segments of a covariant vector in (M_n, L) and f is obviously homogeneous of degree one in L and β . This division in assessment is known as a β change

In 1984, F. Ikeda has zeroed in on the properties of Finsler spaces fulfilling the condition $L^2 C^2 = f(x)$, where L is very far and C is the length of the breeze vector C_i . In 1991 he has mulled over the condition: $L^2 C^2 = \text{non zero clear}$ which is more grounded than the withdrawing condition considered.

A two layered Berwald space is a depiction of such a Finsler space with consistent end LC. A hypothesis of brand name orthonormal outline field on n-layered Finsler space has been considered and is called 'Miron outline' by Matsumoto.

In three-layered Finsler space there are head scalars H, I, J in which the hard and fast H and I is LC, gathered brought head scalar, where as in four-layered Finsler space there are eight focal scalars H, I, J, K, H, I, J, K in which the total H, I and K is LC. Correspondingly there are three h-vector fields and three v-vector fields in four-layered Finsler space.

Consider the problem

$$\begin{aligned} \text{(OPT) minimize} \quad & f(x) \\ \text{subject to} \quad & g_i(x) \leq 0, \quad i = 1, \dots, g \\ & h_j(x) = 0, \quad j = 1, \dots, h, \end{aligned}$$

where f, g_i, h_j have continuous partial derivatives. Let x^* be a feasible point of OPT such that the set of vectors

$$\{\nabla g_i(\bar{x}) \mid g_i(\bar{x}) = 0, i = 1, \dots, g\} \cup \{\nabla h_j(\tilde{x}) \mid j = 1, \dots, h\}$$

is linearly independent. If x^* is a local minimum of OPT, then there exists a g-vector μ and a h-vector λ , such that

- (i) $\mu \geq 0$,
- (ii) $\mu_i g_i(\tilde{x}) = 0, i = 1, \dots, g$ and
- (iii) $\nabla f(\tilde{x}) + \sum_{i=1}^g \mu_i \nabla g_i(\tilde{x}) + \sum_{j=1}^h \lambda_j \nabla h_j(\tilde{x}) = 0$.

If only equality constraints are present (like in the unconstrained version UCP), the first two conditions are empty, and the Karush-Kuhn-Tucker condition boils down to the classical theory of Lagrange multipliers.

Theorem 1 $p = Mx^*G$ minimizes f over $CP(G)$ if and only if there exists a q-vector λ and a $|G|$ - vector G and such that

- (i) $\mu_G \geq 0$,
- (ii) $\mu_i \tilde{x}_i = 0, i \in G$ and
- (iii) $\nabla f(\rho) M_G = \mu_G^T - \lambda^T A_G$.

Proof. The 'only if' part is a direct application of Proposition 4.4, which in general gives only a necessary condition for the existence of a minimum. Due to the special nature of our problem, this condition is also sufficient here. To see this, let $p = M_G x'_G$ be any feasible point satisfying (i), (ii) and (iii) and consider any other feasible solution $p' = M_G x'_G$. Then

$$\nabla f(\rho)(\rho' - \rho) = \nabla f(\rho) M_G (\bar{x}'_G - \bar{x}_G) = \mu_G^T (\tilde{x}'_G - \tilde{x}_G) - \lambda^T A_G (\tilde{x}'_G - \tilde{x}_G) = \mu_G^T \tilde{x}'_G \geq 0$$

because $\mu_G, \tilde{x}'_G \geq 0$, so p is a minimum.

All this requires the gradients of the constraints that are active at p i.e. that hold with equality at p to be linearly independent, so that $p = M_G x'_G$ is a regular point. This is achieved by our nondegeneracy assumption. Assume $\{i \mid \tilde{x}_i = 0\} = F \subseteq G$. Then x' is actually feasible for $CP(G - F)$, therefore the rows of A_{G-F} are linearly independent by non-degeneracy. This implies that the rows of A_G , together with the unit (row) vectors $e_i, i \in F$, are linearly independent, and these are exactly the gradients under consideration.

Now we can prove the main lemma that allows us to fit CP into the LP-type framework.

Lemma 1 Let $\rho := \rho(G) = M_G \tilde{x}_G, \mu_G, \lambda$ according to Theorem 4.5. Then

$$z(G \cup \{j\}) > z(G) \text{ if and only if } \lambda^T A_j + \nabla f(\rho) M_j < 0.$$

Proof. Let $\rho' = M_{GU(j)} \tilde{x}'_{GU(j)}$ be any feasible solution to $CP(G \cup \{j\})$. Then we can write

$$\begin{aligned} \nabla f(\rho)(\rho' - \rho) &= \nabla f(\rho) \left(M_{GU(j)} \tilde{x}'_{GU(j)} - M_G \tilde{x}_G \right) \\ &= \nabla f(\rho) M_G (\tilde{x}'_G - \tilde{x}_G) + \nabla f(\rho) M_j \tilde{x}'_j \end{aligned}$$

$$\begin{aligned}
&= (\mu_G^T - \lambda^T A_G)(\tilde{x}'_G - \tilde{x}_G) + \nabla f(\rho) M_j \tilde{x}'_j \\
&= (\mu_G^T - \lambda^T A_G) \tilde{x}'_G + \lambda^T b + \nabla f(\rho) M_j \tilde{x}'_j \\
&= \mu_G^T \tilde{x}'_G + \lambda^T A_j \tilde{x}'_j + \nabla f(\rho) M_j \tilde{x}'_j. \quad (1.1)
\end{aligned}$$

If $z(G \cup \{j\}) > z(G)$ then p is not optimal for $CP(G \cup \{j\})$ by Lemma 1 we can choose

ρ' (with $\tilde{x}'_j > 0$) such that

$$0 > \nabla f(\rho)(\rho' - \rho) = \mu_G^T \tilde{x}'_G + \lambda^T A_j \tilde{x}'_j + \nabla f(\rho) M_j \tilde{x}'_j \geq \lambda^T A_j \tilde{x}'_j + \nabla f(\rho) M_j \tilde{x}'_j$$

since $\mu_G, \tilde{x}'_G \geq 0$. This in turn means $0 > \lambda^T A_j + \nabla f(\rho) M_j$

Now assume that $z(G \cup \{j\}) = z(G)$ and let $B \subseteq G$ be inclusion minimal with $z(B) = z(G)$. This implies that p has a representation

$$\rho = M_G \tilde{x}_G = M_B \tilde{x}_B + M_{G-B} \tilde{x}_{G-B}, \text{ with } \tilde{x}_B > 0, \tilde{x}_{G-B} = 0,$$

and if we enter the lemma with this representation, we get $u_B = 0$. Let

$\rho' = M_{GU\{j\}} \tilde{x}_{GU\{j\}} = M_{B \cup \{j\}} \tilde{x}_{B \cup \{j\}}$ be any feasible solution of $CP(B \cup \{j\})$ with $x'_j > 0$. Such a p'

exists by our nondegeneracy assumption: $\{A_B x_B = b\}$ is a proper subspace of $\{A_{B \cup \{j\}} x_{B \cup \{j\}} = b\}$

can be obtained by slightly perturbing x'_B , keeping the values at coordinates with subscripts in B

positive. P' is in particular feasible for $CP(G \cup \{j\})$ and since p was assumed to be optimal for

$CP(G \cup \{j\})$, Lemma 1 gives us

$$\begin{aligned}
0 \leq \nabla f(\rho)(\rho' - \rho) &= \mu_G^T \tilde{x}'_G + \lambda^T A_j \tilde{x}'_j + \nabla f(\rho) M_j \tilde{x}'_j \\
&= \mu_B^T \tilde{x}'_B + \lambda^T A_j \tilde{x}'_j + \nabla f(\rho) M_j \tilde{x}'_j \\
&= \lambda^T A_j \tilde{x}'_j + \nabla f(\rho) M_j \tilde{x}'_j.
\end{aligned}$$

because $\mu_B = 0$. Now $\tilde{x}'_j > 0$ implies $\lambda^T A_j + \nabla f(\rho) M_j \geq 0$.

Theorem 2 (H, -z) is an LP-type problem, according to Definition .

Proof. Since for $F \subseteq G$, any feasible solution to CP(F) is feasible for CP(G), we get $z(F) \geq z(G)$, and this is monotonicity. Note that the inequalities are not in the usual direction, since we are actually talking about -z.

To see locality, fix $F \subseteq G \subseteq H$ with $z(F) = z(G)$

Then $p(G) = p(F) = M_G x'_G = M_F x'_F$. Consider λ and μ_G for CP(G). Then, $z(G \cup \{j\}) < z(G)$ is equivalent to $z(F \cup \{j\}) < z(F)$ are good for CP(F), and λ and μ_F

To apply Algorithm, RF-LPtype to CP, two more ingredients are necessary: improvement query and basis improvement. Although we have not explicitly characterized the bases of (H, -z), these are the inclusion minimal sets B that define a certain finite z-value.

Given basis B and j, we know that some vector exists with $z(B \cup \{j\}) < z(B)$ if and only if $\lambda^T A_j + \nabla f(\rho) M_j < 0$, and this criterion seems to be the most natural choice for the improvement query, provided such a λ is given to us. This is the case if we simply store a suitable λ , with every basis B, and ensure that the basis improvement does not only deliver a new basis B' but a corresponding vector λ' as well.

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