

THE HYDRODYNAMICS OF CAPILLARY RISE USING NEUMERICAL METHOD

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Abstract

The capillary rise phenomena have many applications in diverse areas, such as civil engineering, oil recovery, textile, and others. Researchers' research therefore has always been in the both theoretical as well as functional aspect of capillary rise hydrodynamics. In this research its hydrodynamic degree was studied for simulations on two and single-phase fluids using the lattice-Boltzmann method. The goal of such analysis regarding simulations was to properly established the relation between the wetting i.e. solid-liquid as well as the gas-liquid (surface tension). It is this analysis that we see how much the lattice-Boltzmann method has the advantage of simulating regarding the very well familiar capillary rise phenomena, and thus system was evaluated in a narrow capillary pipe on to an uprising fluid.

I INTRODUCTION

Many natural forces and anthropogenic impacts are highly dependent upon on capillary effect , i.e. the potential of liquids to penetrate the wettable walls via finer pores and cracks, and also to be extracted from those with unweathered walls. That is the capillarity which brings water to the upper layer of soil, moves sap in plants and paves the way for the operation of the pens. Awareness of capillarity laws is applicable in the fields of oil extraction, civil engineering, textile fabric dyeing, ink printing and many others. This demonstrates the growing interest in the subject from industry and basic science. Therefore the capillary rise phenomena seems to be of broad practical and theoretical attention in recent years (1-5), with implementations extended from basic capillary rise as well as imbibition (insertion of liquid in droplet form into porous material) up to the droplet spread as well as other wetting-related

phenomena. Major theories related with analytical studies for capillary rise have been established very earlier (6), but latest analytical and simulation techniques gave unique perspective into to this issue: the first lattice-gas automation models (7-11) upon this numerical side, and now the lattice-Boltzmann methods (10, 12-14). Now there are manypaths to introduce interactions amongst fluid's particles and also between particles of fluid with the environment (15–22), and also the methods have also been verified experimentally, particularly in the form of particle suspension (23) and flow in complicated geometrical (24–26).

We recognize capillary phenomenon in the current study and are proposing a model for them. After introduction firstly, we describe the theoretical hydrodynamic structure briefly in Section 2, to which we will relate our results and provide detailed technical information of simulations. Section 3 describes the findings while Section 4 and Section 5 provide review and conclusion.

II CAPILLARY PHENOMENON AND STIMULATION MODEL

Naturally, the most simple example regarding capillary phenomenon is the growth in term of fluid' level inside the capillary-tube, and this process has an critical role especially as liquid's dropletenters theporous content. Since capillary-rise theory is well developed, it provides a benchmark testregarding the methods which are used for simulate imbibition into the porous media. As perWashburn's classical review (27), fluid which is incompressible viewed as a Poiseuille's flow (28). Considering the upward increase of liquid (incompressible) inside a capillary pipe, a start can be consider from the equation of Hagen-Poiseuille for a formed pipe flow at ΔP (change in pressure) during drop,

$$\frac{dQ}{dt} = \frac{\pi \Delta P r^4}{8 \mu_f (h + h_+)} \quad (1)$$

In equation, volumetric flow rate is $dQ/dt = \pi r^2 dh/dt$; h = liquid column's height which is rising w.r.t. liquid surface's level outside pipe while h_+ = immersed capillary pipe length inside liquid, μ_f = liquid viscosity and r = pipe radius.

Overall decrease in pressure is expressed as capillary pressure + the static pressure exerted due to gravity:

$$\Delta P = \frac{2\gamma \cos \theta_d}{r} - \rho_f g h, \quad (2)$$

Where γ = surface tension; θ_d = dynamic contact angle and ρ_f = fluid density. The contact angle is constant in classical capillary rise theory, but in phenomenologically revised fashion (27) of this theory. As the contact angle changes along velocity thus it is called dynamic contact angle. And by combining the eq. (1) and (2), eq. (3) mention below was obtained.

$$8\mu_f(h+h_*)\frac{dh}{dt} = 2r\gamma \cos \theta_d - r^2 \rho_f g h. \quad (3)$$

By adding both entrance as well as inertial effects (28), and by terms rearranging, eq. (3) becomes

$$\cos \theta_d = \frac{1}{2\gamma} \left(\rho_f r h \frac{d^2 h}{dt^2} + \frac{8\mu_f(h+h_*)}{r} \frac{dh}{dt} + \frac{1}{4} \rho_f r \left(\frac{dh}{dt}\right)^2 + \rho_f r g h \right). \quad (4)$$

Eq. (3) is Washburn equation. This is used to compare height of simulated column with dynamic contact angle.

Inertial forces are ignored in our system's overdamped limit (29), to metvariable values. Asymptotically, at long times ($t \rightarrow \infty$), we get eq (5) when $dh/dt=0$,

$$h_\infty = \frac{2\gamma \cos \theta_\infty}{\rho_f g r}, \quad (5) \quad \text{Where} \quad \theta_\infty = \lim_{t \rightarrow \infty} \theta_d.$$

Because of the irregeular discretization as well as the sharp density variance, perticularly for radius r , measurement of θ_d accurately via simulated density field is difficult. For determination (indirect) of θ_d , we 1st apply the 1-D Reynolds transport theorem for control volume so that the rate of change for device momentum can be estimated. Upper control

surface shifts with liquid column's meniscus (no control-volume outflow) as well as the lower surface of control at lower pipe endis fixed. Then rate of total momentum change within the control volume is –

$$\frac{d}{dt}(m\mathbf{v})_{\text{sys}} = \frac{d}{dt} \left[\int_{CV} \mathbf{v}\rho dV \right] + \int_{CS} \mathbf{v}\rho(\mathbf{v} \cdot \mathbf{n})dA, \quad (6)$$

Where total fluid mass inside the control volume = $m=m(t)$; fluid' svelocity of control volume = CV and controlvolumes surface area = CS . After integration eq (7) we get as follows-

$$\begin{aligned} \frac{d}{dt} \left[\int_{CV} \mathbf{v}\rho_f dV \right] &= \rho_f \pi r^2 \left(h \frac{d\mathbf{v}}{dt} + \mathbf{v} \frac{dh}{dt} \right) = \frac{d(m\mathbf{v})_{cv}}{dt}, \quad (7) \\ \int_{CS} \mathbf{v}\rho(\mathbf{v} \cdot \mathbf{n})dA &= -\mathbf{v}(\rho_f \pi r^2 v). \end{aligned}$$

Where v = liquid' s velocity while n = unit vector normal to the inlet controlsurface. By assuming constant velocity over the control surface, wegeta new eq for θ_d byplacingeq. (4) into eqs. (6) and (7),

$$\cos \theta_d = \frac{1}{2\pi r \gamma} \left[\frac{d(mv)_{cv}}{dt} - \frac{3}{4} \rho_f \pi r^2 v^2 + 8\pi \mu_f (h + h_+)v + \rho_f \pi r^2 gh \right]. \quad (8)$$

Equation (8), a right form in Ref. (12), determine θ_d via simulated $h(t)$. The results, however, remain same, particularly for long times, as the speed of rise is less. The position of gas-liquid interface or column height $h(t)$ determined by density profile' s function in vertical direction as a turning point of the least-squares fit.

It addressed a variety of empirical associations for wetting content, describing the dynamic contactangle θ_d as capillary number' s function $Ca = v\mu/\pi$ during spreading so that the advancing contact angle θ_a is the liquid spreading at the $v \rightarrow 0^+$ limit.

We used the term widely accepted in studies (29) regarding capillary-rise,

$$\cos \theta_d = \cos \theta_a - A Ca^B, \quad (9)$$

In above eqA as well as B are constants. Bysimulations, the dependence on θ_a and Ca of θ_d was tested, by which between them above relation was found.

III RESULT

The following simulations were reported for radii of pipe $r = 2, 5$ and 10 while the maximum domain size was $50 \times 50 \times 50$, and $100 \times 100 \times 300$ for pipe radii $r = 20$. The relaxation parameter in all capillary rise, $\tau = 1$ was simulations, unless specified, the adhesive variables were $G = -0.15$ and $W = -0.1$. This culminated in $\rho_f / \rho_g \approx 20$, with the bulk density $\rho_f = 2.25$, surface tension $\gamma = 0.085$ and viscosity $\mu_f = 0.375$ of liquid phase. For the presentation of the results in dimensionless units, the dimensional analysis was done for the variables (g, ρ_f, h, t, μ_f and γ) group. Accordingly, we defined the characteristic time $= t_0 = \mu_f^3 / \rho_f \gamma^2 \approx 3.2$, velocity $= v_0 = \gamma / \mu_f \approx 0.23$ and height $h_0 = \mu_f^2 / \rho_f \gamma \approx 0.74$. And inthe presence of gravity a dimensionless variable $g = \mu_f^4 g / \rho_f \gamma^3$ is used.

Figure 1 of the pipes having different radii velocity profile, and compared them with the White's analytical results (28). This velocity profile calculated from a constant flow of two- or single-phase fluid between 2 infinite parallel platesat its equilibrium density and constant body forcereagrding each lattice point, created the flow in the 2-phase modelwithout any phase separation. In figure 2, of the density profile, there was no bulk density of liquid anywhere in narrow pipe with radius $r = 2$. However, for radius $r = 5, 10$ and 20 , at poor adhesion forces, such as $W = -0.1$, the decay regarding density near the inside of pipe walls was compared. With decreasing radius, thebulk density also decreased the same proportion for liquid. We found that the velocity profile (simulated) reached towards the theoretical curve to increase adhesion, and in the density profile boundary effects decreased (as seen in the curves for radius $r = 20$ as seen in Figure 2). The fluid'sdensity in the 1st layer which is next to the wall has increased with the adhesion (not shown), but the extent of the effect was similar on the wall (liquid layer having thickness of aboutsome spacing in lattice) density. In 3 and 4 figures,the dynamic touch angle and the height of the column are represented as simulation time functions for radius $r = 5$ and 20 . Our result also displayed the findings, with and without the influence of gravity, for comparison while maintaining contant $W = -0.1$. The

capillary rise velocity with period for both null- and non-zero-gravity is in Figure 5. The first column accelerated rapidly, and approximately $t^{1/3}$ then decayed to stationary state. However it takes time and simulating more to correctly adjust the exponent. The acceleration was the result of the pipe being rapidly inserted into the device; decline in non-zero gravity velocity was almost completely independent from radius of capillary.

IVDISCUSSION

We initially modelled a 3-D, 2-phase fluid system using the lattice-Boltzmann method (12), with periodic lateral boundaries and no pipes. The simulation code was already checked for flow through porous media, single-phase fluid and several benchmark results of different studies (30). After a certain number of iterations, the pipe was inserted when the system entered the equilibrium state and the simulation proceeded until the capillary increase was saturated (cf. the snapshots in the Figures 3 and 4 insets for $r=5$ and 20 , respectively). A significant question is about the variance in the radius of capillary in the 2-phase flow model affects the dynamics of the flow. We measured the velocity profile for pipes with different radii to answer this question and correlated it with the analytical results (12) (see Figure 1). In Figure 1 the complete lines also display the velocity profile and analytical results for Poiseuille flow (12). A comparison of analytical results suggested that the velocity profile in stimulation results of this study had the right parabolic shape (Poiseuille). This relative variance increased for the boundary effects as decrease in radius was predicted. Strong boundary-layer influence was the explanation for this deviation. The adhesive force described in the 2-phase lattice-Boltzmann model equation and produces a low density liquid layer on pipe's surface. We not expect great results for pipe having radius $r = 2$, due to very low resolution, and for strong adhesion both radius 5 and 10 were very weak as seen figure 2 for density profile. Column height was decrease in as suggested from eq (3) with increase in pipe size. Without gravity, as eq (3) would have predicted, the column grew more rapidly with increasing radius of the shaft. In addition, there was an increase in column height, which is supposed to increase pipe size. The strong lines in Figures 3 and 4 indicate eq (4)'s respective numerical solutions, where eq (8) determined the complex contact angle θ_d . If the contact angle was maintained fixed, a reasonable agreement could only be achieved between the

Washburn equation as well as the simulation data for a short time window up to $t / t_{\infty} \approx 1000$. By using θ_d in the Washburn equation from eq. (8), there was strong agreement was found for large radius to the last data points where due to increase in interface velocity some variance occurred near the end of the pipe. At the start of simulations, which can be seen in figure 3 and figure 4, we had $\cos\theta_d = 0$, or $\theta_d = \pi/2$. After that the contact angle θ_d associated with Ca decreased or decreased with rising time. The steady state contact angle was quickly reached in a few 100 time steps from the total simulation time (about fifty thousand time steps) particularly in the presence of gravity. Rising of $\cos\theta_d$ at limited scale this resulted the liquid is hitting the pipe end. For long periods and small capillary numbers which mean slow interface speeds, a constant as expected has been approached by θ_d . An improvement in steady state contact angle for raising the pipe length, is unphysical and it is because of the complexity of calculating the exact angle from simulation data. The relative value of the other resistive forces in eq (4) for stronger gravity, a decline and a more stable behaviour of θ_d was more consistent. This supports the notion that our simulation model has very different frictional forces from those assumed in the hydrodynamic derivation of eq. (8).

V CONCLUSION

The capillary rise phenomenon can also be studied by lattice-Boltzmann method numerically, at the level of hydrodynamic. However, for practical kinetics due to discrete effects one requires very thick (in lattice units) tubing. The pipe diameter should be at least 30 lattice units, for the parametrization used here. Future work involves validation or alteration of the velocity profile (theoretical) at walls of a narrow capillary having strong adhesive forces. Somewhat thinner pipes are suitable for the static or unchangeable properties in of gravity's presence, whereas thicker pipes are required in the case of strong adhesion.

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List of Figures: -

Figure no. 1. A typical example of the velocity profile of the fully developed flow of a single-phase ($W = G = g = 0$) fluid, and of a two-phase ($W = -0.1, G = -0.15, g = 0$) fluid, between two parallel plates.

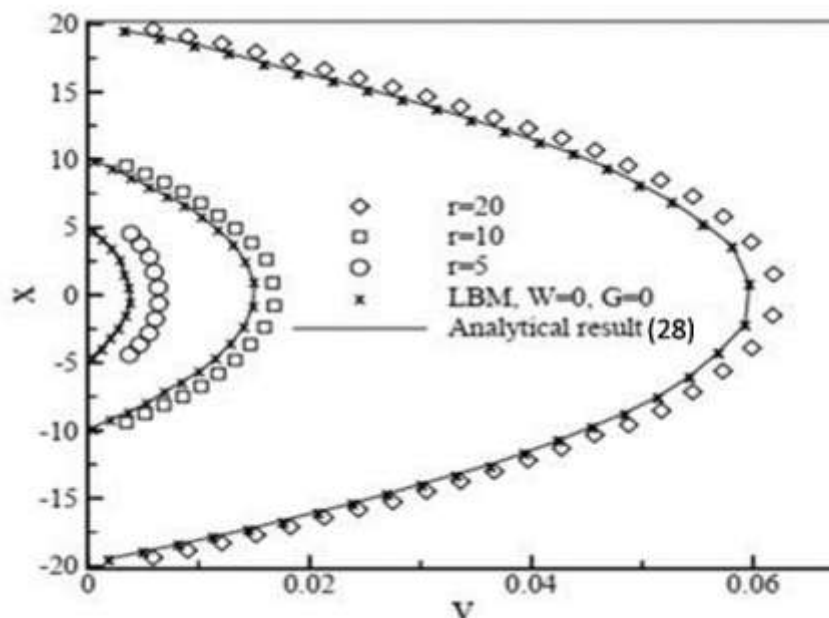


Figure no. 2. The density profiles across the capillary pipe for radii $r = 2, 5, 10$ and 20 as functions of distance from the centerline of the pipe.

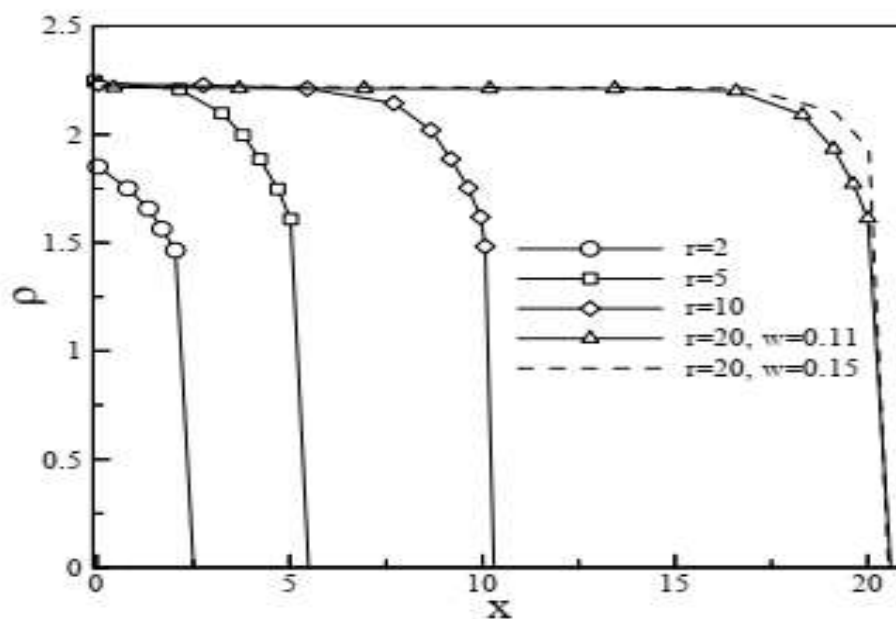


Figure no. 3. The height of the column and the dynamic contact angle as functions of simulation time for the pipe radius $r = 5$. The inset shows three snapshots of the capillary rise: initial, intermediate, and steady state (side view).

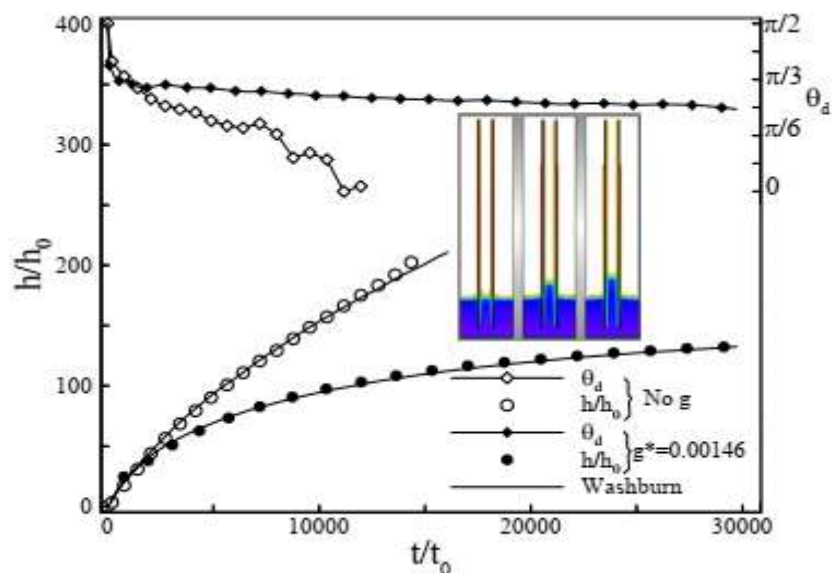


Figure no. 4. The height of the column and the dynamic contact angle as functions of simulation time for the pipe radius $r = 20$. The inset shows three snapshots of the capillary rise: initial, intermediate, and steady state (side view).

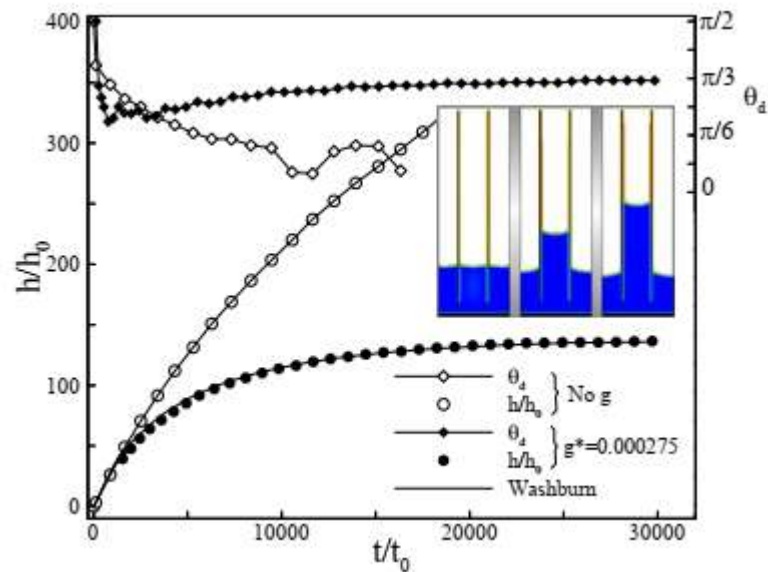


Figure no. 5. Normalized velocity of the column as a function of simulation time.

